or about 6.1 kilometers. The distance is easily seen to be initially decreasing, so that the minimum distance occurs for a positive value of t.

3 Three dimensional Euclidean space \mathbb{R}^3

Consider a third directed segment e_3 of length 1 along with the pair e_1, e_2 discussed in Section 1, which is orthogonal to both e_1, e_2 . We can now label any point in space as (x_1, x_2, x_3) : this is the point reached by starting at the origin, moving distance x_1 (with appropriate interpretation according to sign) in direction e_1 , then x_2 in direction e_2 and then x_3 in direction e_3 . See Figure 16.



Figure 16. Points of three-dimensional space as ordered triples.

Think of e_1, e_2 as pointing east and north on the (flat) earth and e_3 as pointing skywards. Now identify points in space with triples of real numbers to get \mathbb{R}^3 . Formally, \mathbb{R}^3 is the set of ordered triples $\boldsymbol{x} = (x_1, x_2, x_3)$ with each x_i real. Again, we do not distinguish points from directed segments from **0** to \boldsymbol{x} , so \mathbb{R}^3 consists of vectors; and again, we may not always distinguish \boldsymbol{x} from the translate whose initial point is $\boldsymbol{a} = (a_1, a_2, a_3)$ and terminal point $(x_1 + a_1, x_2 + a_2, x_3 + a_3)$ (Figure 17). A double use of Pythagoras's theorem, for the triangles with vertices $\mathbf{0}, (0, x_2, 0), (x_1, x_2, 0)$, and vertices $\mathbf{0}, (x_1, x_2, 0), (x_1, x_2, x_3)$ leads to the formula for the length $|\boldsymbol{x}|$ of vector \boldsymbol{x} (Figure 18):

(8)
$$|\boldsymbol{x}| = (x_1^2 + x_2^2 + x_3^2)^{1/2}$$

For, in the second triangle, $|\boldsymbol{x}|^2 = ((x_1^2 + x_2^2)^{1/2})^2 + x_3^2 = x_1^2 + x_2^2 + x_3^2$.



Figure 17. Translate of a vector in \mathbb{R}^3 .



Figure 18. Double application of Pythagoras's theorem.

Definition 5 The sum of $\boldsymbol{a} = (a_1, a_2, a_3)$ and $\boldsymbol{b} = (b_1, b_2, b_3)$ is

$$a + b = (a_1 + b_1, a_2 + b_2, a_3 + b_3).$$

Geometrically, $\mathbf{a} + \mathbf{b}$ is at the terminal point of the vector \mathbf{b} if \mathbf{b} is placed with initial point at \mathbf{a} . Alternatively, the description of $\mathbf{a} + \mathbf{b}$, as the fourth vertex of the parallelogram with vertices $\mathbf{0}, \mathbf{a}, \mathbf{b}$, that we used in \mathbb{R}^2 , is valid. This is often referred to as the **parallelogram law of addition**. Subtraction of \boldsymbol{z} from \boldsymbol{y} is defined by

$$(\boldsymbol{y} - \boldsymbol{z}) + \boldsymbol{z} = \boldsymbol{y}$$

Thus

$$m{y} - m{z} = (y_1 - z_1, y_2 - z_2, y_3 - z_3).$$

It is clear that the distance from z to y is |y - z|.

Definition 6 The scalar product cx, where c is real and x is in \mathbb{R}^3 , is

$$c\boldsymbol{x} = (cx_1, cx_2, cx_3).$$

We can, as before, describe $c\mathbf{x}$ as the vector pointing in the same direction as \mathbf{x} , but with length c times that of \mathbf{x} , if c > 0; or the opposite direction, with length -c times that of \mathbf{x} , if c < 0. This depends on the formula

$$|c\boldsymbol{x}| = |c| |\boldsymbol{x}|$$

which we can get in a very similar way to the proof in \mathbb{R}^2 :

$$|c\boldsymbol{x}| = ((cx_1)^2 + (cx_2)^2 + (cx_3)^2)^{1/2} = |c|(x_1^2 + x_2^2 + x_3^2)^{1/2} = |c| |\boldsymbol{x}|.$$

You can probably guess the formula that we use to define inner product. It is

Definition 7 The inner product of u and v is

$$\boldsymbol{u}\cdot\boldsymbol{v}=u_1v_1+u_2v_2+u_3v_3.$$

This is consistent with Definition 4 if we think of \mathbb{R}^2 as being the same as the set of all $(x_1, x_2, 0)$ (or, the set of all $x_1 \mathbf{e}_1 + x_2 \mathbf{e}_2$) where x_1 and x_2 are real.

Note that the equation (4) from \mathbb{R}^2 ,

$$|\boldsymbol{u}| = (\boldsymbol{u} \cdot \boldsymbol{u})^{1/2},$$

holds good in \mathbb{R}^3 .

The angle *a* between nonzero vectors $\boldsymbol{u}, \boldsymbol{v}$ can be defined by drawing a plane that contains $\boldsymbol{0}, \boldsymbol{u}, \boldsymbol{v}$ and measuring *a* (between 0 and π) in that plane.

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Proposition 5 We have

$$\boldsymbol{u} \cdot \boldsymbol{v} = |\boldsymbol{u}| |\boldsymbol{v}| \cos a.$$

Proof. We may repeat the proof of Proposition 3 verbatim.

'Verbatim' means 'word for word.' When you want to use for yourself a proof along these lines, bear in mind that students regularly arrive at wrong conclusions this way. If you try it with Proposition 4, you arrive at the false conclusion that

$$\boldsymbol{u}\cdot\boldsymbol{x} = \boldsymbol{u}\cdot\boldsymbol{a}$$

is the equation of a line in \mathbb{R}^3 (it is a plane; see below!). Thus you have to be very careful that arguments still work in a new context.

As in \mathbb{R}^2 , for *nonzero* vectors \boldsymbol{u} and \boldsymbol{v} the relation

(9)
$$\boldsymbol{u} \cdot \boldsymbol{v} = 0$$

is equivalent to $\boldsymbol{u}, \boldsymbol{v}$ being perpendicular. We say \boldsymbol{u} and \boldsymbol{v} are **orthogonal** if (9) holds.

Example 8 The angle between the vectors (1,7,b) and (-2,2,1) is $a = \cos^{-1}(1/3)$. Find b.

Solution. We know that

$$(1,7,b) \cdot (-2,2,1) = |(1,7,b)| |(-2,2,1)| \cos a$$

= $|(1,7,b)| |(-2,2,1)|1/3.$

Thus

$$-2 + 14 + b = (1^2 + 7^2 + b^2)^{1/2} (2^2 + 2^2 + 1)^{1/2} 1/3;$$

$$b + 12 = (b^2 + 50)^{1/2}.$$

If we square both sides and cancel b^2 we find that

$$24b + 144 = 50; \ b = -47/12.$$